

Lecture 3 Introduction to Linear Dynamical Systems

Written by pornrat

Wednesday, 13 July 2016 08:45 - Last Updated Wednesday, 13 July 2016 08:47

{youtube}zWHzaXfC4HQ{/youtube}

Introduction to applied linear algebra and linear dynamical systems, with applications to circuits, signal processing, communications, and control systems. Topics include: Least-squares approximations of over-determined equations and least-norm solutions of underdetermined equations. Symmetric matrices, matrix norm and singular value decomposition. Eigenvalues, left and right eigenvectors, and dynamical interpretation. Matrix exponential, stability, and asymptotic behavior. Multi-input multi-output systems, impulse and step matrices; convolution and transfer matrix descriptions.

□□□□□ : <http://www.stanford.edu/class/ee263/>

□□□□□ : <https://youtu.be/zWHzaXfC4HQ>

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